Carbon-Aware Operation of Resilient Vertical Farms in Active Distribution Networks

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Abstract—Vertical farming is an emerging sustainable solution to enhance the resilience of the food supply and mitigate the carbon emissions of the agriculture sector amidst population growth, geopolitical risks, and climate change concerns. The proximity of food production to consumers enhances food supply resilience. Besides, the potential to leverage renewable resources to energize Vertical Farms (VFs) paves the way to mitigating their food carbon emissions. At the same time, VFs will introduce new challenges and opportunities within Active Distribution Networks (ADNs). While the electricity demand will increase within the ADN, the flexibility in VF's electricity demand provides system operators with demand-side management opportunities. This paper proposes a model to explore the demand of various systems within a VF and their coordination with other assets within the ADN, such as Electric Vehicles (EVs) and photovoltaic (PV) systems. To this end, a framework to procure the optimal operation schedule of VFs under demand and solar generation uncertainties with convexified AC power flow constraints is presented. It is shown that the proposed framework also enhances the dispatchability of renewable Distributed Energy Resources (DERs). The formulated two-stage robust optimization problem is reformulated as a Mixed-Integer Second-Order Cone Programming (MISOCP) problem to be solved by reliable offthe-shelf solvers. It is shown that the demand response of VFs can mitigate the carbon emissions of the electricity and agriculture sectors by up to 70% and decrease the operation cost of the electricity network by 10% for the IEEE-33 bus system compared to utilizing an inflexible schedule for VFs.

Index Terms-demand response, distribution network, vertical farms, uncertainty, sustainable communities.

NOMENCLATURE

Sets

Set of all loads / loads connected to bus i $\mathcal{D}/\mathcal{D}_i$ $\mathcal{E}|\mathcal{E}_i$ Set of all EV fleets / fleets connected to bus i $\mathcal{F}/\mathcal{F}_i$ Set of all vertical farms / VFs connected to bus i $\mathcal{G}/\mathcal{G}_i$ Set of all feeders connected to the network / bus i $S|S_i$ Set of all PVs / PVs connected to bus i \mathcal{L}_{f} Set of all levels of vertical farm f \mathcal{T} Set of time horizon \mathcal{Z} Set of electricity generation resources δ_i Set of adjacent buses to bus i Variables

Lifting operator terms of SOCP relaxation c, s

- Real/imaginary part of voltage phasor of bus *i* e_i, f_i
- E_e^t Energy of the fleet of EV e at time t (MWh)
- Status of systems within VF f at time t
- Real power dispatch of solar s at time t (MW)
- $\begin{array}{c}
 I_{e}^{r} \\
 I_{(.),f}^{t} \\
 P_{s}^{t} \\
 P_{e,t}^{c}
 \end{array}$ Real charging power of EV fleet e at time t(MW)

- Real power demand of the lighting/irrigation system $P_{f,li/ir}^t$ of VF f at time t
- $P_{l,f}^{a,t,+/-}$ Real power demand of air conditioniner of level lof VF f at t working in heating/ cooling mode
- Exchange heating power of level l of farm f at t
- $\begin{array}{c} P_{l,f}^{X,t} \\ P_{l,f}^{h,t} \\ P_{l,f}^{h,t} \end{array}$ Real power demand of the dehumidification system of level l of VF f at time t
- $Q_{f,li/ir}^t$ Reactive power demand of the lighting/ irrigation system of VF f at time t
- $Q_{l,f}^{a/h,t}$ Reactive power demand of the air conditioner/ dehumidifier of level l of VF f at time t
- P_f^t, Q_f^t Real/reactive power demand of VF f at time t (MW/MVAR)
- P_g^t, Q_g^t Real/reactive power dispatch of generation unit q at time t (MW/MVAR)
- P_{ij}^t, Q_{ij}^t Real/reactive power flow between bus i and j at time t (MW/MVAR)
 - Temperature of level l within VF f at time t (K)
- $\boldsymbol{\theta}_{l,f}^t \\ \boldsymbol{\varsigma}_{l,f}^t$ Absolute humidity of level l of farm f at time t $\left(\frac{lit}{m^3}\right)$
- μ,λ Dual variables

Parameters

- A_{l}^{f} The cultivable area of level l within VF f (m^2)
- $A_{l,f}^w$ The surface of walls of level l within VF f (m^2)
- B/GSusceptance / conductance matrix (S)
- Budget of uncertainty (%) BoU
- The specific heat capacity of air $(\frac{MWh}{kqK})$ C_a
- $C_E^{z,t}$ Carbon emissions of electricity generation z at t $\left(\frac{MT}{MW}\right)$
- The gravitational force $\left(\frac{m}{s^2}\right)$ g
- i_1^f The required LED light intensity for level l of vertical farm f (lux)
- $K_{l,f}^w$ Thermal conductivity of level l walls within VF f $\left(\frac{MW}{mK}\right)$
 - Maximum charging power of fleet of $EVs \ e \ (MW)$
- Forecasted real power of load d at time t (MW)
- Real power demand of load d at time t (MW)
- $\begin{array}{c} \overline{p_e^c} \\ p_D^{t,0} \\ p_D^t \\ p_D^t \\ \overline{p}_s^{t,0} \end{array}$ Forecasted available solar power for $PV \ s$ at time t(MW)
 - Available solar power for $PV \ s$ at time t (MW)
- $\overline{p}_s^t \\ q_D^t$ Reactive power of load d at time t (MVAR)
 - Traveling power consumption of EV e at time t (MW)
- $\begin{array}{c} p_{e,t}^{tr} \\ p_{l,f}^{t} \end{array}$ Fertilization demand of level l of farm f at time t(MW)
- Electricity demand of the dehumidifier to remove 1 p_w liter water form the air (MW)
- T_h Total seconds in an hour (sec)

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- Evaporated water from crops of level l within VF fat time t (lit)
- $X_{l,f}^w$ The thickness of walls of level l within VF f (m) Inverter efficiency of EV fleet e
- $\gamma_e^{\cdot} \\ \Delta_h^f$ The height VF f (m)
- The efficacy of the LED lamps $(\frac{lux}{MW})$
- The efficiency of water pump p in VF f (%)
- The efficiency of air conditioning systems of VF f
- $\begin{array}{c} \epsilon_l \\ \eta_p^f \\ \eta_a^f \\ \theta_{out}^t \\ \rho_z^t \end{array}$ Outside temperature of VF at time t (K)
- Share of generation type z at time t
- Time-of-Use cost of electricity at time $t\left(\frac{\$}{MWh}\right)$ α_t

I. INTRODUCTION

He growth in the world's population will lead to fundamental changes in energy and food security. The world population is predicted to reach 9 billion by 2050 [1], and 80% of the population will reside in urban areas [2]. Thus, the demand for fresh food in cities will grow. Climate change concerns over deforestation and geopolitical conflicts will lead to more limited access to agricultural [3]. Thus, an emerging challenge is to present a sustainable, efficient, and and costeffective food supply chain. The growing trend of "vertical farming" as a potentially sustainable food supply solution [4] aims to address several challenges, including but not limited to shedding the restrictions on agricultural products due to seasonal weather patterns, natural disasters, temperature changes [5], water supply, and irradiance intensity, overcoming transportation challenges [6], and the need to significantly enhance yields [7]. The VF concept envisions the sprawling crop farms of old condensed into much smaller factory-like sites where conditions can be optimized and yields are remarkably increased [8], [9]. Vertical farming is a concept that involves cultivating plants on vertically inclined surfaces, where it is resilient against weather-related distress and geopolitical disruptions impacting the food supply chain network. Some argue that the ultimate goal of vertical farming is to provide fresh food for the entire population of the world without concern for climate change and disasters[10].

Transportation, agriculture, and the electricity sectors are among the largest global emitters of greenhouse gases, and they can account for 70% of the global greenhouse gas emissions by 2050 [11]. The Paris Agreement in 2015 set out a desire to limit the global temperature rise to $1.5^{\circ}C$ above pre-industrial levels. Yet, based on the current trends in emissions and national policy commitments, the Paris targets are in jeopardy [12]. Utilizing vertical farms can mitigate the carbon emissions of the agriculture and transmission sectors by eliminating the need for harmful pesticides, which account for 33% of the total indirect carbon emissions of farm products [13], decreasing the food miles traveled [14], eliminating the usage of combustion engine machinery, (e.g., tractors), and increasing the yield of crops [1]. In [15], the authors present a roadmap to decrease the carbon emissions of the agricultural sector. This paper aims to illustrate how the increase in the

penetration level of VFs will contribute to a reduction in the carbon emissions of smart communities.

With the projected increase in the utilization of VFs in urban areas, investigating the challenges and opportunities of utilizing these new loads for the electricity grid plays a vital role in the operation and planning problems of the electricity network. Thus, presenting a demand-side model to present the performance of different systems in a VF is the key to studying those challenges and opportunities. The systems that should be considered within a VF are 1) lighting; 2) irrigation and fertilization; 3) air conditioning; and 4) dehumidification system [4], as presented in Fig. 1. Coordinating the energy consumption of these loads with the operation of the electricity ADN can enhance the operational planning characteristics of the network in terms of renewable dispatchability and demand response. Currently, there is a gap in the literature to investigate the demand response potentials of various systems within a VF as a flexible asset to the smart grid. This paper presents a model exploring different aspects and ambient features of a VF to become a flexible asset to the smart grid. The proposed model for VFs is utilized for coordinating the flexible demand of VFs with other assets within the ADN to enhance the resilience of food and energy supply. This paper shows that utilizing VFs as the main resource to meet the food demand will consume about 30% of the share of the electricity demand. The future smart grid is expected to



Fig. 1: Control unit and electricity demand of different systems within a vertical farm

include independent entities, such as prosumers, who will plug in their generation or consumption devices at their discretion. The penetration level of uncertain *DERs* in the power system is increasing. Particularly, increasing the penetration level of EVs within the ADN will deteriorate the power quality [16]. A practical tool to address these challenges is demand response. Demand response refers to encouraging end-users through a specific tariff or program to change their normal electricity consumption patterns, i.e., consume less power during peak times or shift their electricity demand to off-peak hours to flatten the demand curve [17]. Demand response transforms consumers into players with a more active role in energy management by leveraging the potential flexibility in electricity loads [18]. Several flexible demand entities, including data centers[19], EV charging stations[20], [21], residential EVs [22], cooling and heating loads [23], and residential loads [24] are presented as demand-responsive loads in the literature to remedy the challenges raised by DER uncertainty within the ADN. Besides, several authors have modeled the air conditioning systems within residential loads with the focus of utilizing the model of air conditioning systems for demand response [25]. However, this paper models the irrigation and lighting systems within a VF as demand-responsive assets.

The numerous operational advantages of demand response are enumerated in the literature and are also applicable to VFs. First, VF demand response could mitigate the difference between peaks and valleys of power demand. Second, adjusting the internal schedules of the VF could enhance the dispatchability of renewable DERs, similar to those achieved by utilizing EVs [26]. This paper presents the model of VFs as a demand-responsive asset in coordination with uncertain DERs such as EVs and PV systems within an ADN. Several control systems, including lighting and irrigation systems, can operate as shiftable loads within a VF. To ensure proper crop vield and growth, the air conditioning and dehumidification systems are constantly controlled to maintain temperature and humidity within the desired range. Scheduling VF based on the unit cost of electricity aims to minimize their operation costs. Besides, their carbon emissions may be mitigated by operating during hours of abundant renewable energy.

This paper aims to address the following questions: What would be the benefit of coordination between the electricity demand of systems within VFs and other assets within the ADN? Can the flexibility of the demand within a VF provide utilities with demand-side management opportunities to enhance renewable dispatchability? Is the electricity distribution network ready for the emerging electricity demand of VFs?The main contributions of this paper are listed as follows.

- The model of various systems within a vertical farm is presented and formulated as a demand-responsive asset. It is shown that coordinating *VFs* with *DERs* and other demands within the *ADN* enhances the dispatchability of renewable *DERs*, decreases the unfortunate renewable generation curtailments, and thus decreases the overall carbon emissions and operating cost of the *ADN*.
- A framework is presented to examine the preparedness of *ADN* for various scenarios of *VF*s penetration level considering demand and solar generation uncertainties, where the objective function is carbon emissions minimization or operation cost minimization. Here, demands within the *VF*s across the *ADN* are scheduled over a selected set of worst-case uncertainty realizations. Furthermore, it is illustrated that coordinated scheduling of *VF*s mitigates the adverse impact of uncertainties in renewable generation and demand on the operation of *ADN*.
- The impact of utilizing VFs, as a sustainable food supply solution on the carbon emissions of the electricity and agriculture sectors is evaluated. Besides, the performance of the proposed framework on other emerging challenges within the ADN including the increase in electricity demand of EVs due to the push toward transportation electrification, is presented.

II. PROBLEM FORMULATION

In this paper, first, models of different systems in VFs are suggested. Then, the optimal operation schedule of shiftable systems within VFs is proposed and coordinated with other assets within the ADN. The optimal operation scheduling problem for the VFs considering the uncertainties of demand and solar generation units, is a two-stage robust optimization problem. Here, the schedule of the irrigation and lighting systems within a VF are here-and-now decision variables that are procured in the first-stage problem. Each type of crop requires a specific *daily* intake of light and water to ensure optimal growth, which must be satisfied. The power dispatch of the feeder bus, the utilized solar generation, the demand of air conditioning and dehumidification systems, and the served demand are the wait-and-see decision variables, which are determined based on the uncertainty realization in the secondstage problem. Here-and-now decision variables are the firststage decisions that will be made at the time of deciding the daily schedule of the shiftable systems within VFs. Once the decisions are made, they cannot be adjusted during the operation period of the problem. The wait-and-see decision variables are the second-stage decisions, which could change given the realization of uncertain variables. Therefore, the main criterion to distinguish them is the necessity of making the decision at the time of determining the daily schedule for the VF. Two different objectives are considered for the optimal scheduling problem, which is a two-stage robust optimization problem: carbon emissions minimization and operation cost minimization.

A. Objective Function

The presented discussion aims to address the operation preferences of cost minimization and carbon emission minimization.

1) Carbon emissions minimization problem: The objective function of the optimal operation scheduling problem for VFs with respect to carbon emissions is proposed in (1). The firststage problem minimizes the operation carbon emissions of the shiftable systems within VFs by procuring the optimal operation schedule of VFs. As concerned in the second-stage problem, the carbon emissions of the ADN and VFs depends on the generation mix, which consists of various resources, ρ_z^t , (e.g., natural gas, renewable resources, imports of connected transmission networks, etc.), the total power dispatch of the feeder at time t, and the corresponding carbon emissions of each source to generate 1 p.u. of electricity, $C_E^{z,t}$, at time t. The carbon emissions of the generation mix is changing over the operation horizon. For instance, the carbon emissions of the generation mix is low during sunny hours due to the increase in the share of solar generation units, and it is high due the to low participation of renewable generation during the night. The first term in the carbon minimization function (1) presents the shiftable carbon emissions of the irrigation and lighting systems of VFs over a time horizon T, respectively. The real power demand of the irrigation and lighting systems, i.e., shiftable systems within VF, depends on the first-stage binary decision variables, the status of lighting and irrigation systems $(I_{l,f}^{li,t}, I_{f}^{ir,t})$, at time t. The electricity demand of the irrigation and fertilization systems of farm f at time t depends on the status of the irrigation system, the total water demand of VF f in a day, m_w^f , the height of the farm, Δ_h^f , the gravitational force, g, the efficiency of the water pumps, and the total number of irrigation periods, τ_{ir}^{f} , as well as the fertilization demand at each irrigation period. The electricity power demand of the lighting system of VF f at time t depends on the required LED light intensity for the growth of crops at each level, i_l^f , the cultivated area, A_l^f , the efficacy of LEDs, ϵ_l , and the status of the lighting system at level l of farm f at time t, $I_{l,f}^{li,t}$. The last term presents the second-stage carbon emissions minimization of the *ADN* over the worst-case realization of uncertain variables (i.e., demand and solar availability).

$$\min_{I_{l,f}^{li,t},I_{f}^{ir,t}} \sum_{t \in \mathcal{T}} \left[\sum_{f \in \mathcal{F}} \sum_{z \in \mathcal{Z}} C_{E}^{z,t} \left(\left(\frac{m_{w}^{f} g \Delta_{h}^{f}}{\tau_{ir}^{f} T_{h} \eta_{p}^{f}} + \sum_{l \in \mathcal{L}_{f}} p_{l,f}^{t} \right) I_{f}^{ir,t} + \sum_{l \in \mathcal{L}_{f}} \frac{A_{l}^{f} i_{l}^{f}}{\epsilon_{l}} I_{l,f}^{li,t} \right) \rho_{z}^{t} \right] + \max_{p_{D}^{t}, \overline{p}_{s}^{t}} \min_{P_{g}^{t}} \sum_{t \in \mathcal{T}} \sum_{g \in \mathcal{G}} \sum_{z \in \mathcal{Z}} C_{E}^{z,t} P_{g}^{t} \rho_{z}^{t} \quad (1)$$

2) Operation cost minimization problem: The objective function of the optimal operation scheduling for VFs with the minimum operation cost is proposed in (2). The first two terms in (2) present the first-stage problem that minimizes the operation cost of the shiftable systems within VFs over \mathcal{T} . The operation cost of the VFs depends on the Time-of-Use (ToU) price of the electricity, α_t , and the real power demands of lighting and irrigation systems over \mathcal{T} . In the first-stage problem, the optimal schedule of the irrigation and lighting systems ($I_{l,f}^{li,t}, I_f^{ir,t}$) are procured to minimize the operation cost of VFs. The last term of the objective function presents the second-stage problem that minimizes the operation cost of ADN over \mathcal{T} over the worst-case realization of uncertain variables (i.e., demand and solar generation).

$$\min_{I_{l,f}^{li,t},I_{f}^{ir,t}} \sum_{t \in \mathcal{T}} \left[\sum_{f \in \mathcal{F}} \alpha_{t} \left(\left(\frac{m_{w}^{t} g \Delta_{h}^{J}}{\tau_{ir}^{f} T_{h} \eta_{p}^{f}} + \sum_{l \in \mathcal{L}_{f}} p_{l,f}^{t} \right) I_{f}^{ir,t} + \sum_{l \in \mathcal{L}_{f}} \frac{A_{l}^{f} i_{l}^{f}}{\epsilon_{l}} I_{l,f}^{li,t} \right) \right] + \max_{p_{D}^{t},\overline{p}_{s}^{t}} \min_{P_{g}^{t}} \sum_{t \in \mathcal{T}} \sum_{g \in \mathcal{G}} \alpha_{t} P_{g}^{t} \quad (2)$$

3) Joint cost and carbon emissions minimization problem: The joint cost and carbon emissions objective function of the optimal operation scheduling for VFs is proposed in (3), where the first two terms are for the first-stage problem and the last term represents the second-stage problem. Here, γ is the monetizing coefficient for carbon emissions.

$$\min_{\substack{I_{l,f}^{li,t}, I_{f}^{ir,t} \\ t \in \mathcal{T}}} \sum_{t \in \mathcal{T}} \left[\sum_{z \in \mathcal{Z}} (\alpha_{t} + \gamma C_{E}^{z,t} \rho_{z}^{t}) \sum_{f \in \mathcal{F}} \left(\left(\frac{m_{w}^{f} g \Delta_{h}^{f}}{\tau_{ir}^{f} T_{h} \eta_{p}^{f}} + \right) \sum_{l \in \mathcal{L}_{f}} p_{l,f}^{t} \right) I_{f}^{ir,t} + \sum_{l \in \mathcal{L}_{f}} \frac{A_{l}^{f} i_{l}^{f}}{\epsilon_{l}} I_{l,f}^{li,t} \right] + \frac{\max_{p_{D}^{t}, \overline{p}_{s}^{t}} \sum_{P_{g}^{t}} \sum_{t \in \mathcal{T}} \sum_{g \in \mathcal{G}} \sum_{z \in \mathcal{Z}} (\alpha_{t} + \gamma C_{E}^{z,t} \rho_{z}^{t}) P_{g}^{t} \qquad (3)$$

B. Vertical Farms Model

The model of systems within VFs is suggested in (4)-(8), which consists of lighting, irrigation and fertilization, air conditioning, and dehumidification systems. Note that in the proposed model, the electricity demand of the lighting and irrigation systems is 95% of the total VFs electricity demand [27]. The main advantage of VFs compared to conventional farming is their resilience against weather-related stress, as they maintain the crop's temperature within a threshold range of $27^{\circ}C$ to $31^{\circ}C$. In [28], the authors show that stress thermal time of more than 4000 °C-minutes decreases crop yield by more than 60%. The total real and reactive electricity demand of VF f at time t is the sum of the real and reactive electricity demand of all the systems in the VF as proposed in (4a) and (4b), respectively. Note that the variable after each colon in front of constraints shows the dual variable corresponding to that constraint. The details of the model associated with each system within the VF are given as follows:

$$P_{f}^{t} = P_{f,li}^{t} + P_{f,ir}^{t} + \sum_{l \in \mathcal{L}_{f}} P_{l,f}^{a,t,+} + P_{l,f}^{a,t,-} + P_{l,f}^{h,t} : \lambda_{P}^{f,t}$$
(4a)

$$Q_f^t = Q_{f,ir}^t + \sum_{l \in \mathcal{L}_f} Q_{l,f}^{a,t} \qquad \qquad : \lambda_Q^{f,t}$$
(4b)

1) Lighting system: The model of the lighting system of VF f is suggested in (5). The electricity power demand of the lighting system of VF f at time t depends on the required LED light intensity for the growth of crops at each level, the cultivated area, the efficacy of LEDs, and the status of the lighting system at each level, as presented in (5a). The crops of each level of VF f need a specific duration of light per day to grow as presented in (5b).

$$0 \le P_{f,li}^t = \sum_{l \in \mathcal{L}_f} \frac{A_l^f i_l^f}{\epsilon_l} I_{l,f}^{li,t} \qquad : \underline{\mu}_{f,t}^{P_{li}}, \lambda_{f,t}^{P_{li}}$$
(5a)

$$\sum_{t \in \mathcal{T}} I_{l,f}^{li,t} = \tau_l^f \tag{5b}$$

2) Air conditioning system: The air conditioning system of level l of VF f is modeled in (6). The heating or cooling power of the air conditioning system to control the air temperature of level l of farm f is modeled in (6a). Here, $P_{l,f}^{a,t}$ is the heating or cooling power required at level l of farm f at time t. Note that $P_{l,f}^{a,t,+}, P_{l,f}^{a,t,-}$ are non-negative variables to model the absolute power demand of the air conditioning system working in heating and cooling modes. The exchange heating power, $P_{l,f}^{X,t}$, depends on the temperature difference of each level and outside, the walls' or glasses' thickness, area, and thermal conductivity, as presented in (6b). The maximum and minimum temperatures of each level of the VF depend on the type of cultivated crop. Based on the desired maximum and minimum temperature for each level, the temperature of each level of farm f at time t is limited in constraint (6c). The electricity demand of the air conditioning system is a nonnegative variable. Thus, it is the sum of the real power demand of the cooling and heating modes of the air conditioning system as presented in (6d). The reactive power demand of the air conditioning system at level l of farm f depends on the power factor of the related air conditioning system, $PF_{l,f}^a$, and the real power demand of the air conditioning system as presented in (6e).

$$P_{l,f}^{X,t} + P_{l,f}^{a,t} = \frac{m_{l,f}^{a}C_{a}(\theta_{l,f}^{t} - \theta_{l,f}^{t-1})}{\eta_{a}^{f}} \qquad \qquad : \lambda_{l,f}^{P_{a},t} \quad (6a)$$

$$P_{l,f}^{X,t} = K_{l,f}^w A_{l,f}^w (\theta_{out}^t - \theta_{l,f}^t) / X_{l,f}^w \qquad \qquad : \lambda_{l,f}^{P_o,t}$$
(6b)

$$\underline{\theta}_{l,f} \leq \theta_{l,f}^{t} \leq \overline{\theta}_{l,f} \qquad : \underline{\mu}^{\theta_{l}^{(t)}}, \overline{\mu}^{\theta_{l}^{(t)}}$$
(6c)

$$P_{l,f}^{a,t} = P_{l,f}^{a,t,+} - P_{l,f}^{a,t,-} \qquad :\lambda_{l,f}^{pn,t} \quad (6d)$$

$$Q_{l,f}^{a,t} = \frac{\sqrt{1 - PF_{l,f}}}{PF_{l,f}^{a}} (P_{l,f}^{a,t,+} + P_{l,f}^{a,t,-}) \qquad :\lambda_{l,f}^{Q_{a},t}$$
(6e)

3) Irrigation system: The model of the irrigation system of farm f at time t is suggested in (7). The required hours for irrigation of crops of VF f is limited in (7a). The electricity demand of the irrigation and fertilization systems of farm f at time t depends on the quantity of water required in each irrigation period, the height of the farm, and the efficiency of the water pumps, as shown in (7b). The reactive power demand of the irrigation system of each farm depends on the power factor of pumps utilized on the farm, PF_{ir}^{f} , and the real power demand of the irrigation system as shown in (7c).

$$\sum_{t \in \mathcal{T}} I_f^{ir,t} = \tau_{ir}^f \tag{7a}$$

$$0 \le P_{f,ir}^t = \left(\frac{m_w^T g \Delta_h^J}{\tau_{ir}^f T_h \eta_p^f} + \sum_{l \in \mathcal{L}_f} p_{l,f}^t\right) I_f^{ir,t} : \underline{\mu}_{f,t}^{P_{ir}}, \lambda_{f,t}^{P_{ir}} \quad (7b)$$

$$Q_{f,ir}^{t} = \frac{\sqrt{1 - PF_{ir}^{f^{2}}}}{PF_{ir}^{f}}P_{f,ir}^{t} \qquad : \lambda_{f,t}^{Q_{ir}}$$
(7c)

4) Dehumidification system: Since VFs are indoor facilities full of crops, the absolute humidity of the air increases due to the evaporated water from the crops. Thus, the de/humidification system only works in dehumidification mode. The model of the dehumidification system at level lof farm f is modeled in (8). The electricity demand of the dehumidification system at level l of farm f at time t, $P_{l,f}^{h,t}$, depends on the evaporated water from crops, and the required electricity demand of the dehumidification system to remove 1 liter of water from the air as presented in (8a). The absolute humidity of each level of farm f at time t, $\varsigma_{l,f}^{t}$, is limited in (8b).

$$P_{l,f}^{h,t} - W_{l,f}^{e,t} p_w = (\varsigma_{l,f}^t - \varsigma_{l,f}^{t-1}) p_w \qquad : \lambda_{l,f}^{P_h,t}$$
(8a)

$$\underline{\varsigma}_{l,f} \leq \underline{\varsigma}_{l,f}^{t} \leq \overline{\varsigma}_{l,f} \qquad \qquad : \underline{\mu}^{\underline{\varsigma}_{l}^{j,v}}, \overline{\mu}^{\underline{\varsigma}_{l}^{j,v}} \tag{8b}$$

C. EV Charging and DER Model

The solar generation power at time t is limited by the available solar power at time t as presented in (9) and is adopted from [29].

$$0 \le P_s^t \le \overline{p}_s^t \qquad \qquad : \underline{\mu}_t^s, \overline{\mu}_t^s \qquad (9)$$

The real power charging of fleet of $EVs \ e$ at time $t, P_{e,t}^c$, is capped by the multiplication of the maximum charging power of fleet of $EVs \ e$ and the ratio of connected EVs in the fleet (10a). The energy balance of fleet of $EV \ e$ at time t depends on the real power charging, efficiency of the inverter, and traveling power consumption of the fleet at each time as presented in (10b). The energy of fleet of $EVs \ e$ at time t is limited as shown in (10c) and is adopted from [29].

$$0 \le P_{e,t}^c \le \overline{p_e^c} R_c^t \qquad \qquad : \underline{\mu}_{c,t}^e, \overline{\mu}_{c,t}^e \qquad (10a)$$

$$E_{e}^{t} = E_{e}^{t-1} - (p_{e,t}^{tr} R_{d}^{t} - \gamma_{e}^{c} P_{e,t}^{c}) \qquad : \lambda_{e}^{t}$$
(10b)

$$\underline{E}_e \le E_e^t \le E_e \qquad \qquad : \underline{\mu}_t^e, \overline{\mu}_t^e \qquad (10c)$$

D. Distribution Network Model

The real and reactive nodal balance equations in their AC form are presented in (11a) and (11b), respectively. The real and reactive power flow constraints of line (i, j) of the *ADN* in their AC form are presented in (11c) and (11d), respectively, and are adopted from [30].

$$\sum_{s \in \mathcal{S}_i}^{\text{here attract adopted liquid}} P_g^t = \sum_{d \in \mathcal{D}_i}^{\text{here attract adopted liquid}} p_D^t + \sum_{f \in \mathcal{F}_i} P_f^t + \sum_{e \in \mathcal{E}_i} P_{e,t}^c + (G_{ii} + \sum_{j \in \delta_i} G_{ij})((e_i^t)^2 + (f_i^t)^2) + \sum_{j \in \delta_i} P_{ij}^t \quad (11a)$$

$$\sum_{g \in \mathcal{G}_{i}} Q_{g}^{\iota} = \sum_{d \in \mathcal{D}_{i}} q_{D}^{\iota} + \sum_{f \in \mathcal{F}_{i}} Q_{f}^{\iota} + \sum_{j \in \delta_{i}} Q_{ij}^{\iota}$$
$$- (B_{ii} + \sum_{j \in \delta_{i}} B_{ij})[(e_{i}^{t})^{2} + (f_{i}^{t})^{2}] \quad (11b)$$

$$P_{ij}^{t} = -G_{ij}(e_{i}^{t^{2}} + f_{i}^{t^{2}}) + G_{ij}(e_{i}^{t}e_{j}^{t} + f_{i}^{t}f_{j}^{t}) - B_{ij}(e_{i}^{t}f_{j}^{t} - e_{j}^{t}f_{i}^{t})$$
(11c)
$$Q_{ij}^{t} = B_{ij}(e_{i}^{t^{2}} + f_{i}^{t^{2}}) - B_{ij}(e_{i}^{t}e_{j}^{t} + f_{i}^{t}f_{j}^{t}) -$$

The AC nodal balance and power flow equations have bilinear terms that make the robust optimization problem a nonconvex optimization problem. A set of *SOCP* lifting variables is introduced in (12) to relax these bi-linear terms.

$$c_{ii}^{t} := (e_{i}^{t})^{2} + (f_{i}^{t})^{2}; \quad c_{ij}^{t} := e_{i}^{t}e_{j}^{t} + f_{i}^{t}f_{j}^{t}; \quad s_{ij}^{t} := e_{j}^{t}f_{i}^{t} - f_{j}^{t}e_{i}^{t}$$
(12)

The *SOCP* relaxed form of the nodal balance and power flow equations is presented in (13) by leveraging the *SOCP* lifting variables introduced in (12). As the *SOCP* relaxation method is tight for acyclic radial distribution networks [31], [30], the rendered solution of the optimal operation scheduling problem for the *ADN*s is exact.

$$\sum_{s \in S_i} P_s^t + \sum_{g \in \mathcal{G}_i} P_g^t = \sum_{d \in \mathcal{D}_i} p_D^t + \sum_{f \in \mathcal{F}_i} P_f^t + \sum_{e \in \mathcal{E}_i} P_{e,t}^e + (G_{ii} + \sum_{j \in \delta_i} G_{ij})c_{ii}^t + \sum_{j \in \delta_i} P_{ij}^t \qquad : \lambda_i^{P,t}$$
(13a)

$$P_{ij}^t = -G_{ij}c_{ii}^t + G_{ij}c_{ij}^t + B_{ij}s_{ij}^t \qquad \qquad :\lambda_{ij}^{p,t} \quad (13c)$$

$$Q_{ij}^{t} = B_{ij}c_{ii}^{t} - B_{ij}c_{ij}^{t} + G_{ij}s_{ij}^{t} \qquad \qquad :\lambda_{ij}^{q,t}$$
(13d)

The relationship between the *SOCP* lifting variables, and the second-order cone relaxation of the relating the *SOCP* lifting terms are presented in (14a) and (14b), respectively. Besides, the *SOCP* relaxed form of the voltage limits of each bus is presented in (14c).

$$c_{ij} = c_{ji} \qquad , \qquad s_{ij} = -s_{ji} \qquad : \lambda_{ij}^{c,t}, \lambda_{ij}^{s,t} \quad (14a)$$

$$\left\| \begin{array}{c} 2c_{ij} \\ 2s_{ij}^t \\ c_{ii}^t - c_{jj}^t \\ \end{array} \right\| \le c_{ii}^t + c_{jj}^t \qquad : \mu_{ij}^{c,t}, \mu_{ij}^{s,t}, \mu_{ij}^{cc,t}, \mu_{ij}^{cone,t}$$
(14b)

$$\underline{V}_{i}^{2} \leq c_{ii}^{t} \leq \overline{V}_{i}^{2} \qquad \qquad : \underline{\mu}_{v_{i}}^{t}, \overline{\mu}_{v_{i}}^{t} \qquad (14c)$$

The uncertainty of the available power of solar generation unit s at time t and the uncertainty of demand d at time t are limited by (15a)-(15b), respectively.

$$\overline{p}_s^t \in [\overline{p}_s^{t,0} - \Delta_p^{s,t}, \overline{p}_s^{t,0} + \Delta_p^{s,t}]$$
(15a)

$$p_D^t \in [p_D^{t,0} - \Delta_p^{d,t}, p_D^{t,0} + \Delta_p^{d,t}]$$
(15b)

III. SOLUTION METHOD

The SOCP relaxed form of the optimal operation scheduling problems presented in Section II is a two-stage robust optimization problem. Here, the Column-and-Constraint Generation Algorithm (C&CGA) [32] is leveraged to tackle the uncertainty of demand and available solar generation. The relaxed form of the optimal operation scheduling of VFs problems is presented in the compact form of the two-stage robust optimization problem, where x is the first-stage binary decision variable, y is the second-stage continuous decision variable, and u is the uncertain variable realized in the secondstage problem. In Section III-B, c, e, b, A, E, d, F, G, h, H are corresponding known coefficient vectors or matrices. The binary decision variables of the first-stage problem, x, are vectorized representations of the status of the lighting and irrigation systems of each floor at each time slot, as presented in (5b) and (7a), respectively. The objective function (1), (2), or (3) is presented as (16a) and the sets of constraints given in (16b) and (16c) present all constraints with binary decision variables (i.e., first stage binary variables, x) that were formulated in (5a)-(5b) and (7a)-(7b). The set of constraints presented in (16c) captures the second-stage decision variables y vectorized for all indices as well as the realization of uncertain variables u such as demand of power system and solar generation availability and vectorized for all indices. The set of constraints given as (16d) presents the feasibility set of second-stage decision variables.

$$\min_{x} c^T x + \max_{y \in U} (\min_{y} b^T y)$$
(16a)

a.t.
$$Ax + Ey = d, x_i \in \{0, 1\}$$
 (16b)

$$Fx + Gy \ge h - Hu, x_i \in \{0, 1\}$$
 (16c)

$$y \in \Omega(x, u) \tag{16d}$$

Enumerating all scenarios with the different realizations of u is practically challenging. Therefore, to solve the problem presented in (16), an iterative solution method that selects a subset of uncertain variables at each iteration is presented. The size of the subset at each iteration is determined by the BoU. The dual form of the SOCP relaxed representation of the second-stage problem is utilized to determine the worst-case realization in an iteration given the rendered firststage decisions from the current iteration of the algorithm. The details of the algorithm are discussed in Section III.B. The presented C&CGA determines significant scenarios that contribute to the worst realization of the system operation cost or carbon emissions. After the decomposition, the problem consists of a first-stage problem and the second-stage problem, which are shown in (17) and (18), respectively. It should be noted that ψ represents the iteration index.

$$\min_{x} c^{T}x + \gamma$$

$$s.t. \quad \gamma \ge b^{T}y^{(\psi)}$$
(17)

$$Ax + Ey^{(\psi)} = d$$

$$Fx + Gy^{(\psi)} \ge h - Hu^{*(\psi)}$$

$$\forall x \in \Omega_x, y \in \Omega_y$$

$$\max_{u \in U} (\min_{y \in \Omega(x,u)} b^T y)$$

$$s.t. \quad Ax + Ey^{(\psi)} = d$$

$$Fx^* + Gy \ge h - Hu$$

$$(18)$$

Here-and-now decision variables of the first-stage problem are passed through the second-stage problem. The *SOCP* relaxed inner minimization problem of the second-stage problem is reformulated as a maximization problem using its dual form. Therefore, the maximization problem presented in (19)-(27j), will render the worst realization of uncertain variables given the minimization of the inner problem. In an iterative process, the realized uncertainties are added as a column to the firststage problem to update the here-and-now decision variables. Once the C&CGA algorithm is converged, no new column will be added, and the final robust here-and-now decision variables are revealed.

A. Dual Reformulation of SOCP Relaxed Second-Stage Problem

To reformulate the max-min problem in the second-stage problem as a maximization problem, the dual representation of the inner minimization problem is proposed in (19)-(27) assuming that the worst realization of uncertainties occurs at the extreme point within the polyhedral uncertainty set. Note that the variable after each colon in front of dual constraints shows the related primal variables. The objective of the dual problem is presented in (19). Note that the status of the lighting system and irrigation system (i.e., $I_{l,f}^{*li,t}$ and $I_{l,f}^{*ir,t}$) are fixed based on the obtained values by solving the firststage problem.

$$\max_{\substack{U_{s}^{t}, V_{s}^{t}, U_{d}^{t}, V_{d}^{t} \in \mathcal{I} \\ v_{d}^{t}, V_{s}^{t}, U_{d}^{t}, V_{d}^{t} \in \mathcal{I} \\ v_{d}^{t}, V_{s}^{t}, U_{d}^{t}, V_{d}^{t} \in \mathcal{I} \\ v_{d}^{t}, V_{d}^{t}, V_{d}^{t}, V_{d}^{t} \in \mathcal{I} \\ v_{d}^{t}, V_{d}^{t}, V_{d}^{t}, V_{d}^{t} \in \mathcal{I} \\ v_{d}^{t}, V_{d}^{t}, V_{d}^{t}, V_{d}^{t}, V_{d}^{t} \in \mathcal{I} \\ v_{d}^{t}, V_{d}^{t},$$

The dual constraints associated with the real power generated by solar generation unit s at time t is given in (20).

$$\underline{\mu}_t^s - \overline{\mu}_t^s + \sum_{i \in \mathcal{I}_s} \lambda_i^{P,t} = 0 \qquad \qquad : P_s^t \quad (20)$$

The dual constraints associated with the real charging power and energy of the fleet of EV e at time t are presented in (21a) and (21b), respectively.

$$\underline{\mu}^{e}_{c,t} - \overline{\mu}^{e}_{c,t} + \lambda^{t}_{e} - \lambda^{P,t}_{i} = 0 \qquad \qquad : P^{c}_{e,t} \quad (21a)$$

$$\underline{\mu}_{e}^{t} - \overline{\mu}_{e}^{t} + \lambda_{e}^{t} - \lambda_{e}^{t+1} = 0 \qquad \qquad : E_{e}^{t} \quad (21b)$$

The dual constraints related to the total real and reactive power demand of the VF f at time t are presented in (22a) and (22b), respectively.

$$\lambda_P^{f,t} - \sum_{i \in \mathcal{I}_f} \lambda_i^{P,t} \le 0 \qquad \qquad : P_f^t \quad (22a)$$

$$\lambda_Q^{f,t} - \sum_{i \in \mathcal{F}_i} \lambda_i^{Q,t} = 0 \qquad \qquad : Q_f^t \quad (22b)$$

The dual constraints associated with the lighting, air conditioning, irrigation, and humidification systems are presented in (23)-(26b). The dual constraint corresponding to the real power demand of the lighting system of VF f at time t is presented in (23).

$$\underline{\mu}_{f,t}^{P_{li}} + \lambda_{f,t}^{P_{li}} - \lambda_P^{f,t} = 0 \qquad \qquad : P_{f,li}^t \quad (23)$$

The dual constraints related to the total real and reactive demand of the air conditioning system at level l of farm f at time t are presented at (24a) and (24b), respectively. Besides, the dual constraints corresponding to non-negative demand of the air conditioning system working in cooling and heating modes at level l of farm f at time t are presented at (24c) and (24d), respectively. The dual constraints associated with exchange heating power and temperature of l of farm f at time t are presented in (24e) and (24f), respectively.

$$\lambda_{l,f}^{P_{a,t}} + \lambda_{l,f}^{pn,t} = 0 \qquad \qquad :P_{l,f}^{a,t} \qquad (24a)$$

$$\lambda_{l,f}^{Q_a,t} - \lambda_Q^{J,t} = 0 \qquad \qquad : Q_{l,f}^{a,t} \qquad (24b)$$

$$-\lambda_{P}^{f,t} - \lambda_{l,f}^{pn,t} - \frac{\sqrt{1 - PF_{l,f}^{a}}}{PF_{l,f}^{a}} \lambda_{l,f}^{Q_{a},t} \le 0 \quad :P_{l,f}^{a,t,+} \quad (24c)$$

$$-\lambda_{P}^{f,t} + \lambda_{l,f}^{pn,t} - \frac{\sqrt{1 - PF_{l,f}^{a}}^{2}}{PF_{l,f}^{a}} \lambda_{l,f}^{Q_{a},t} \le 0 \quad :P_{l,f}^{a,t,-}$$
(24d)

$$\lambda_{l,f}^{P_{a,t}} + \lambda_{l,f}^{P_{a,t}} = 0 \qquad :P_{l,f}^{X,t} \quad (24e)$$

$$m_{l,f}^{a} C_{a,-R-t+1} = R_{t,-K} K_{l,f}^{w} A_{l,f}^{w} = R_{t,-K} a_{l,f}^{t,t}$$

$$\frac{m_{l,f} \circ a}{\eta_{a}^{f}} (\lambda_{l,f}^{P_{a},t+1} - \lambda_{l,f}^{P_{a},t}) + \frac{m_{l,f} \circ l,f}{X_{l,f}^{w}} \lambda_{l,f}^{P_{a},t} + \underline{\mu}^{\theta_{l}^{f,t}} - \overline{\mu}^{\theta_{l}^{f,t}} = 0 \qquad : \theta_{l,f}^{t} \qquad (24f)$$

The dual constraints related to the total real and reactive demand of the irrigation system at level l of farm f at time t are presented at (25a), (25b), respectively.

$$\lambda_{f,t}^{P_{ir}} + \underline{\mu}_{f}^{P_{ir},t} - \lambda_{P}^{f,t} - \frac{\sqrt{1 - PF_{ir}^{f^{2}}}}{PF_{ir}^{f}} \lambda_{f,t}^{Q_{ir}} = 0 : P_{f,ir}^{t}$$
(25a)
$$\lambda_{f,t}^{Q_{ir}} - \lambda_{Q}^{f,t} = 0 : Q_{f,ir}^{t}$$
(25b)

The dual constraints related to the absolute humidity and demand of the dehumidification system at level l of farm f at time t are presented at (26a), (26b), respectively.

$$p_{w}(\lambda_{l,f}^{P_{h},t+1} - \lambda_{l,f}^{P_{h},t}) + \underline{\mu}^{\varsigma_{l}^{f,t}} - \overline{\mu}^{\varsigma_{l}^{f,t}} = 0 \qquad :\varsigma_{l,f}^{t} \quad (26a)$$
$$\lambda_{l,f}^{P_{h},t} - \lambda_{P}^{f,t} \le 0 \qquad :P_{l,f}^{h,t} \quad (26b)$$

The dual constraints associated with the real and reactive power dispatch of the feeder bus for the carbon emissions minimization problem are presented in (27a) and (27b), respectively. It should be noted that the right-hand side of the dual constraint associated with the real power dispatch of the feeder bus (27a) would be α_t if the objective is to minimize the operation cost of the distribution network. The dual constraints associated with the lifting terms c_{ii}^t , c_{ij}^t , and s_{ij}^t are given in (27c)-(27e), respectively. The dual constraints associated with real and reactive power flow of lines are presented in (27f) and (27g), respectively. The dual SOC cone is presented in (27h). To determine the worst realization of the uncertain variables, binary variables $U_s^t, V_s^t, U_d^t, V_d^t$ are introduced. Each pair of binary variables is mutually exclusive, as shown in (27i). Moreover, the budget of uncertainty limits the combination of the binary variables that yields the worst realization of the uncertain variables, as shown in (27j). Note that $|\mathcal{T}|(|\mathcal{S}|+|\mathcal{D}|)$ represents the total number of uncertain variables.

$$\lambda_i^{P,t} = \sum_{z \in \mathcal{Z}} C_E^{z,t} \rho_z^t \qquad \forall i \in \mathcal{I}_g \qquad \qquad : P_g^t \quad (27a)$$

$$\lambda_i^{Q,t} = 0 \qquad \qquad \forall i \in \mathcal{I}_g \qquad \qquad : Q_g^t \quad (27b)$$

$$(G_{ij}\lambda_{ij}^{p,i} - B_{ij}\lambda_{ij}^{q,i} - (G_{ii} + \sum_{j \in \delta_i} G_{ij})\lambda_i^{r,i} + (B_{ii} + \sum_{j \in \delta_i} B_{ij})\lambda_i^{Q,t} + \underline{\mu}_{v_i}^t - \overline{\mu}_{v_i}^t + \sum_{j \in \delta_i} (\mu_{ij}^{cc,t} + \mu_{ij}^{cone,t}) + \sum_{j \in \delta_i} (-\mu_{ji}^{cc,t} + \mu_{ji}^{cone,t}) = 0 \qquad : c_{ii}^t \ (27c)$$

$$-G_{ij}\lambda_{ij}^{p,t} + B_{ij}^{q,t}\lambda_{ij}^{q,t} + \lambda_{ij}^{c,t} - \lambda_{ji}^{c,t} + 2\mu_{i,j}^{c,t} = 0 : c_{ij}^{t}$$
(27d)
$$-B_{ij}\lambda_{ij}^{p,t} - G_{ij}\lambda_{ij}^{q,t} + \lambda_{ij}^{s,t} + \lambda_{ji}^{s,t} + 2\mu_{i,j}^{s} = 0 : s_{ij}^{t}$$
(27e)

 $i \in \delta$:

$$-\sum_{i\in\mathcal{FB}_{ij}}\lambda_i^{p,t} + \lambda_{ij}^{p,t} = 0 \qquad \qquad :P_{ij}^t \quad (27f)$$

$$-\sum_{i\in\mathcal{FB}_{ij}}\lambda_i^{q,t} + \lambda_{ij}^{q,t} = 0 \qquad \qquad :Q_{ij}^t \ (27g)$$

$$\begin{pmatrix} \mu_{ij}^{c,t} \\ \mu_{ij}^{s,t} \\ \mu_{ij}^{c,t} \end{pmatrix} \leq \mu_{ij}^{cone,t}$$

$$(27h)$$

$$\begin{cases} U_s^t + V_s^t \le 1\\ U_d^t + V_d^t \le 1 \end{cases}$$
(27i)

$$\frac{\sum_{t \in \mathcal{T}} (\sum_{s \in \mathcal{S}} U_s^t + V_s^t + \sum_{d \in \mathcal{D}} U_d^t + V_d^t)}{|\mathcal{T}| (|\mathcal{S}| + |\mathcal{D}|)} \le BoU$$
(27j)

B. Column-and-Constraint Generation Algorithm

By utilizing the dual reformulation of the inner minimization problem of the second-stage problem (18) which is presented in (19)-(27j), the second-stage optimization problem is reformulated and presented in its compact form in (28).

$$\max_{\substack{u,\lambda,\mu\\u,\lambda,\mu}} d^T \lambda - (h - Hu)^T \mu$$
(28)
s.t. $A^T \lambda + E^T \mu = 0$
 $\mu \ge 0$

The binary-to-continuous variable multiplications in (19) are linearized using the method presented in [32]. The C&CGA that was utilized to solve the optimal scheduling problems of VFs is presented in Algorithm 1.

Algorithm 1 Column-and-Constraint Generation 1: Set $LB = -\infty$, $UB = \infty$, initialize u^0 2: $\psi = 0$ 3: while $\frac{UB-LB}{UB} > \epsilon$ do Using $u^{(\psi)}$ solve the first-stage prob. (17) $\rightarrow x^*, \gamma^*$ 4: Set $LB = c^T x^* + \gamma^*$ 5: Using x^* solve the second-stage prob. (28) $\rightarrow u^*, y^*$ 6: Set $UB = c^T x^* + b^T y^*$ 7: Update $\psi + = 1$ 8: Assign $u^{(\psi)} = u^*$ 9. 10: end while

In the first step, the lower bound (LB) and upper bound (UB) are set to $-\infty$ and ∞ , respectively. Besides, the initial value of uncertain binary variables is set to zero. If the convergence condition is not satisfied, solving the master problem (17) procures the optimal scheduling solution for VFs $(I_{l,f}^{*li,t}, I_{f}^{*ir,t})$. The LB is updated based on the solution of the first-stage problem. In the next step, the second-stage problem (28) is solved to procure the subset of the worst-case scenario (i.e., $U_s^{*(\psi+1),t}, V_s^{*(\psi+1),t}, U_d^{*(\psi+1),t}, V_d^{*(\psi+1),t}$). Then, the upper bound of the algorithm is updated using the binary and continuous decision variables procured by solving the secondstage problem. At last, the iteration index, ψ , and $u^{(\psi)}$ will be updated. The algorithm will converge once the difference between the upper and lower bounds of the algorithm divided by the upper bound is equal to or less than a small nonnegative parameter (ϵ) as presented in line 3 of Algorithm 1. Once converged, the first-stage decisions procured in the last iteration are reported as here-and-now decisions. Problems (17) and (28) are MISOCP optimization problems, and they are solved using off-the-shelf conic programming solvers such as Gurobi [33]. Here, a PC is utilized with a Core i7 CPU 4.70 GHz processor, and 48 GB memory.

IV. CASE STUDIES

In this section, the performance of VFs as a demandresponsive load is evaluated for different scenarios. Besides, the challenges and opportunities of utilizing VFs in the ADN are illustrated in the cases. The capability of VFs to increase the dispatchability of *DERs* in an *ADN* with a high penetration level of solar generation units is also demonstrated. Lastly, the coordination of VFs with renewable *DERs* is investigated to mitigate the impact of renewable uncertainties on ADN operations.

A. Test System Configuration

The topology of the modified IEEE 33-bus system is presented in Fig. 2. The test system consists of 33 buses,

32 branches, 7 solar generation units, 32 loads, 4 vertical farms, and 12 EV charging points. The base net demand, solar generation, the share of each electricity generation resource in the generation mix of each hour, and carbon emission trends are set according to the normalized hourly data of California ISO on November 4, 2021 [34]. Given the electricity demand of the ADN without VFs (120 MWh per day), there are 4200 houses in this community, and the average household number is considered 3 [35]. Assuming that each person consumes 2.5 kg of food per day, the food consumption of the community is 31.5 tons per day. Besides, the electricity usage of a 40level VF building with 900 m^2 VF that produces 32 tons of food each day [4] is 48 MWh per day. Thus, the share of the electricity demand of VFs with 100% penetration level in the total electricity demand of the network is roughly 30%. In [36], it is mentioned that the average CO_2 emissions of cultivating 1kg crops is 1.5 metric kg (mkg) CO_2 . Thus, the total carbon emissions of cultivating 31.5 tons of crops per day would be 47 metric tons (mT) per day. In [37], it is mentioned that food in the United States travels about 1500 miles to get from the farm to the consumer. Assuming the transport of 5500kg crops with each truck, 5 miles per gallon for refrigerated trucks, and $0.0127 \text{ mT } CO_2$ -e emission for each gallon of diesel [38], the CO_2 -e of delivering the conventional agriculture produces to this community is 21 mT CO_2 -e. Thus, the total carbon emissions of producing food in the presented community using conventional farming methods is 68 mT CO_2 -e. Thus, the carbon emissions of 1kg food for the conventional farming method is 2.16 metric kg.



Fig. 2: Modified IEEE 33-bus test system

B. The Impact of Vertical Farming on the ADN

Here, two different objective functions are compared. In sections IV-B1 and IV-B2, the objective is to *minimize the total carbon emissions* of the distribution network over 24 hours, while the objective function in sections IV-B3 and IV-B4 is to *minimize the total operation cost* of the distribution network. To illustrate the performance of the proposed *VF* model, three cases are considered as follows.

Case 1- No *VF* is considered and the conventional agriculture fulfills the food demand

Case 2- VFs with inflexible demand schedule of its systems are considered within the ADN as shown in Fig. 2.

Case 3- *VF*s with shiftable demand of lighting and irrigation systems within the ADN.

It should be noted that an inflexible schedule VF refers to the best-practice predetermined schedule that is not flexible to changes in coordination with renewable generation. 1) Analyzing the impact of VF on carbon emissions of food consumption and the distribution network: Utilizing vertical farms decreases the total carbon emissions of the agriculture and transportation sectors. Here, the impact of the VFs on the carbon emissions of the ADN and the carbon emissions of the transportation sector are investigated. Although electricity demand increases with the presence of VFs within the ADN, the overall carbon emitted by the electricity, transportation, and food sectors decreases. Shiftable demand within VF facilitates a further decrease in carbon emissions as it shifts VF's demand into hours with a cleaner electricity generation mix. Note that the penetration level of VFs demonstrates their share of VFs in producing the total food demand in the community.

Total carbon emissions of the smart community due to agricultural activities and electricity demand of the ADN with various penetration levels of VFs are presented in Fig. 3. When there is no VFs in the community, case 1 (i.e., the penetration level of VFs is zero), the agricultural products are obtained from conventional agriculture methods. Fig. 3 shows that the decrease in the carbon emissions of the agriculture sector dominates the increase in the carbon emissions of the ADN with the additional VF demand. Electricity Sector Case3 and Agriculture Sector Case3 present the carbon emissions of *electricity* sector and the carbon emissions of *agriculture* sector when utilized VFs have shiftable demand, respectively. Exclusive community food supply by VFs cuts the total carbon emissions of the electricity and agriculture sectors by 62%. Fig. 3 shows that the total carbon emissions of the community in case 1 is 82.73 mT CO_2 -e. It decreases 12.6% to 72.29 mT CO_2 -e with a 20% supply of the community food demand by VFs. The maximum decrease of 66% to 28.18 mT CO_2 -e is achieved in case 3 (i.e., shiftable VFs with 100%) penetration level). The flexibility in the electricity demand of VFs contributed to 9% the reduction in carbon emissions when the penetration level of VFs is 100%. Besides, the carbon emissions of producing 1kg food decreased 80% from 2.18 metric k.g. CO_2 -e in conventional agriculture to 0.43 metric kg CO_2 -e with demand-responsive VFs.



Fig. 3: Total CO_2 emissions of electricity consumption and farming activities in the smart community

Utilizing VFs at 100% penetration level will shift the carbon

emissions of food production to the electricity sector. In Fig. 3, the emissions of the agriculture sector refer to conventional farming emissions. At 100% penetration level of VFs, the food demand of the community is exclusively met by the VFs. As shown in Fig. 3, there is a 15 mT CO_2 -e increase in emissions of the electricity sector with the increase in electricity demand of VFs at 100% penetration level. However, it is significantly less than 68 mT CO_2 -e emissions of conventional farming in the absence of VFs to serve the same food demand.

Fig. 4 demonstrates how VFs shift their demand based on the CO_2 emissions of the generation mix and the share of renewable generation units. The right Y-axis of Fig. 4 represents the CO_2 emissions associated with electricity generation, specifically the amount of carbon emitted per 10 MWh of electricity generated during the day. The CO_2 emissions of the VFs at time t are calculated as the product of the VFs' demand at time t and the CO_2 -e emissions of the electricity generation at time t. In this scenario, the VF demand is shifted from hours with higher CO_2 emissions to those with lower CO_2 emissions. The green-shaded area shows the hours with reduced demand for the shiftable VFs. The red-shaded area demonstrates the hours with increased demand of the shiftable VFs. The total daily carbon emissions of inflexible schedule VFs is 15.03 mT CO_2 -e while the one procured by shiftable VFs decreases 18.2% to 12.3 mT CO_2 -e. Utilizing [30] to show the tightness of SOCP relaxation in constraint (14b), the minimum relaxation tightness measures for cases 1, 2, and 3 are 9.74, 9.21, and 9.54, respectively, which demonstrate a tight relaxation.



Fig. 4: Shifting the demand of VFs concerning CO_2 emissions

2) Demand-responsiveness of VFs to the CO_2 emissions trend: The presented model for VFs enables a flexible schedule of systems within the VF in response to the CO_2 emissions trends. Fig. 5 compares the performance of the shiftable VFs in the day during summer with one during fall, where the CO_2 emissions trends of the VFs are highly dependent on that of the electricity network.

A different pattern of carbon emissions trend of electricity generation leads to different carbon emissions of 1kg food produced in VFs. In Table I, the carbon emissions of VFs, smart communities, including the electricity and agriculture sectors, and the carbon emissions of cultivating 1 kg of food are presented for different days of the year: 1) May 4th, 2021; 2) August 4th, 2021; 3) November 4th, 2021; and 4)



Fig. 5: Demand-responsiveness of shiftable VFs

February 4th, 2022, normalized according to the data provided by California ISO [34].

 TABLE I

 CARBON EMISSIONS OF THE COMMUNITY IN DIFFERENT DAYS

Day	1	2	3	4
CO_2 -e VFs (mT)	13.41	13.57	13.67	13.65
CO_2 -e Community (mT)	17.3	24.5	28.2	24.7
CO_2 -e 1kg Food (mkg)	0.425	0.431	0.434	0.433

While the carbon emission of conventional farming to provide the food required in the community is 68 metric tons per day, that of VFs presented in Table I for different days has decreased dramatically to less than 14 metric tons per day. It is an interesting observation that VF enables such a reduction in carbon emissions regardless of the season. The carbon emissions of producing 1kg food from conventional farming methods is 2.18 metric kg CO_2 -e while those procured by demand-responsive VFs is decreased more than 79% to less than 0.45 metric kg CO_2 -e across the year. Here, the 0.45 metric kg CO_2 -e emissions of the VFs are calculated based on the carbon emissions of the electricity generation they utilized to cultivate the crops.

3) Performance of demand-responsive VFs in the operation cost minimization problem: Here, the objective function of the problem is to minimize the operation cost of the electricity ADN as presented in (2). Here, VFs adjust their demand curve to minimize the operation cost of the electricity ADN by shifting their electricity demand to hours with lower rates. Fig. 6 a) compares the electricity demand of VFs procured by cost minimization and carbon emissions minimization objective functions, and Fig. 6 b) compares the carbon emissions of the ADN when the goal of VFs is minimizing the carbon emissions or the operation cost of the ADN for different days, where it is shown that the carbon emissions of various days of the year would be different with the cost minimization objective.



Fig. 6: the demand and carbon emissions with various choices of objective functions for Shiftable VFs

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4) Enhance the dispatchability of solar generation by leveraging the flexibility of VFs: A high penetration level of DERs (e.g., 80% for solar generation units) might lead to curtailments within the ADN due to hosting capacity limits. Here, it is shown that utilizing VFs enhances dispatchability of DERs. Fig. 7 illustrates that the curtailed dispatch of solar generation units decreases when VFs are utilized in the ADN. The total demand of VFs at each hour shows that in the sunny hours of the day, VFs demanded more electricity to minimize the solar curtailment. The total curtailed solar dispatch procured for the cost minimization problem without VFs is 37.7MWh for 24 hours. However, the one procured for the cost minimization problem with shiftable VFs decreased from 71% to 10.62MWh.



Fig. 7: The reduction in solar curtailment with shiftable VFs

5) The limitations of ADNs to host VFs: One major challenge of hosting VFs on the ADN is the capability of the electricity network to serve the elevated electricity demand. Fig. 8 showcases the lost load when the VFs with 100% penetration level are utilized to serve the demand for food of the community. Utilizing the demand-responsive VFs mitigates the load shedding of the ADN by shifting the demand. The dramatic reduction in the lost load of the ADN with demand-responsive VFs compared to the inflexible schedule is presented in Fig. 8a. The demand of the VFs procured by the fixed and shiftable models is compared in Fig. 8b. Thus, even with shiftable VFs demand, ADN is not ready to serve VFs with 100% penetration level.

The modified IEEE 33-bus system can support VFs with shiftable demand at 80% penetration level without load shedding. However, the *ADN* can not serve inflexible schedule VFs in peak hours as shown in Fig. 8c. Flexible VFs shifted their load to off-peak hours, as shown in Fig. 8d to prevent load shedding.

6) Joint cost and carbon emissions minimization: The joint cost and carbon emissions objective function of the optimal operation scheduling for VFs is proposed in (3), where the first two terms are for the first-stage problem and the last term represents the second-stage problem. Here, γ is the monetizing coefficient for carbon emissions.

$$\min_{I_{l,f}^{li,t},I_{f}^{ir,t}}\sum_{t\in\mathcal{T}}\bigg[\sum_{z\in\mathcal{Z}}(\alpha_{t}+\gamma C_{E}^{z,t}\rho_{z}^{t})\sum_{f\in\mathcal{F}}\bigg((\frac{m_{w}^{f}g\Delta_{h}^{f}}{\tau_{ir}^{f}T_{h}\eta_{p}^{f}}+$$



Fig. 8: The impact the shift in VF demand with high penetration levels on lost load within ADN

$$\sum_{l \in \mathcal{L}_f} p_{l,f}^t) I_f^{ir,t} + \sum_{l \in \mathcal{L}_f} \frac{A_l^f i_l^f}{\epsilon_l} I_{l,f}^{li,t} \bigg) \bigg] + \\ \max_{p_D^t, \overline{p}_s^t, P_g^t} \sum_{t \in \mathcal{T}} \sum_{g \in \mathcal{G}} \sum_{z \in \mathcal{Z}} (\alpha_t + \gamma C_E^{z,t} \rho_z^t) P_g^t$$
(29)

C. Operation Schedule of Vertical Farms Under Uncertainties

In this case, the uncertainty in demand and solar generation is considered with a deviation from the nominal values and a budget for uncertain variables over the operation horizon. Here, Algorithm 1 converges in 5 iterations with a total solve time of fewer than 30 minutes. The total carbon emissions of the smart community would increase with the introduction of uncertainties. It should be noted that all VFs in the ADN are considered with shiftable demand of the lighting and irrigation systems (i.e., case 3). Here, the total carbon emissions of the smart community in the presence of demand and solar generation uncertainties with 10% deviation and 10% BoU are increased to 29.98 metric tons CO_2 -e from 28.18 metric tons CO_2 -e without it. Fig. 9 a) illustrates that the increase in deviation and BoU results in an increase in total carbon emissions. VFs adjust the operating schedule of their systems to minimize the total carbon emissions of the community, taking uncertainties into account. When the deterministic case solution (i.e., the schedule of VFs' systems) is exposed to a stochastic case with a 5% uncertainty deviation and 20% BoU, the carbon emissions of the VFs increase by 30% (from 26.7 mT to 34.7 mT CO_2 -e).

Fig. 9 (b) illustrates the changes in the VFs' schedule with uncertainty consideration,

where the VFs' schedule shifts towards the early morning hours due to uncertainties in both demand and solar generation units, underscoring the importance of considering these uncertainties when determining the optimal schedule for irrigation and lighting.



Fig. 9: Impact of uncertainties on the schedule of VFs and total CO_2 -e of the ADN

Increasing the deviation of uncertain variables from nominal values increases the carbon emissions of the ADN as well as the smart community. Besides, the adverse impact of uncertainties is more notable at lower penetration levels of VFs as shown in Table II. Here, deterministic case emissions of the VF are compared with those of the uncertain case with 5% Deviation and 20% BoU when the penetration level of VFs is 10% and 80%. It is shown that the adverse impact of uncertainty is mitigated at higher penetration levels of VF.

 TABLE II

 MITIGATING THE ADVERSE IMPACT OF UNCERTAINTY WITH VFs

	10% VF's Pen. Level	80% VF's Pen. Level
Deterministic case emissions (mT CO ₂ -e)	15.14	25.6
Emissions with 5% deviation and 20% BoU (mT CO_2 -e)	16.37	26.7
Adverse impact of uncertainties (%)	8.12	4.43

Adding the CO_2 -e of conventional farming (the remaining 20% of the community food demand) to the total carbon emissions of the ADN procures the total carbon emissions of the community. The total carbon emissions of the community with 80% penetration level of VFs for deterministic and uncertain cases are 42.04 mT and 43.3 mT CO_2 -e, respectively.

V. CONCLUSIONS

In this paper, the model of the electricity demand of vertical farms, as a demand-responsive asset, is presented. Coordinating VFs with other assets within the active distribution network (e.g., solar generation units and electric vehicles) introduces several opportunities and challenges to utilities. The preparedness of the electricity network plays a vital role in expanding vertical farms. A framework to utilize vertical farms in the active distribution network under demand and solar generation uncertainties using AC power flow constraints is presented. The proposed two-stage robust optimization problem is solved by decomposing it using the column and constraint generation algorithm. The dual presentation of the relaxed second-order cone programming problem for the inner minimization problem of the second-stage problem is presented to reformulate the second-stage

problem as a maximization problem. The performance of the model in mitigating the carbon emissions of the agriculture and electricity sectors is compared with conventional agricultural methods. Besides, the merit of utilizing vertical farms as a demand-responsive asset for grid operators is evaluated, where its coordination with other DERs, such as electric vehicles and solar generation units, can lead to 79% decrease in the carbon emissions of food production. Besides, shifting the demand of vertical farms to hours with a cleaner generation mix will decrease the carbon emissions of the electricity network. Moreover, it is illustrated that utilizing shiftable VFs contributes to a significant improvement in the dispatchability of solar generation resources. Finally, it is discussed that, although uncertainty contributes to the increase in carbon emissions, a higher penetration level of vertical farms would mitigate such an adverse impact. The suggested future work is the long-term expansion planning of vertical farms within the distribution network.

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